PRL

Technical Note

TN-84-38

A NOTE ON STEPWISE REGRESSION ANALYSIS PROGRAMMING SYSTEM

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April 1984

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#### A NOTE ON STEPVISE REGRESSICN ANALYSIS PROGRAMMING SYSTEM

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#### ABSTRACT

This note describes a general programming system - 'RACSRS' for stepwise regression analysis, which has been developed in FORTRAN IV. The system has been thoroughly tested using IBM 360/44. The package can also handle any nonlinear model that can be transformed to linear.

#### Key words:

- 1. Stepwise multiple regression analysis
- 2. Best curve fitting
- 3. Model building

## I. Introduction:-

In Ordinary Multiple Regression Analysis (OMRA) all variables under consideration will be in the model. Situations often arise where a number of predictor (independent) variables are available (sometimes more than the number of observations) and the model builder wishes to select a few of the best predictors (statistically significant or otherwise) to be in the model.

The note describes the Stepwise Multiple Regression

Analysis (SLRA) which is a very useful statistical tool for
this purpose. The principle underlying it is that off least
squares. This differes from OMRA in that only statistically
significant variables are introduced in the model.

The technique introduces one variable at a time into the model provided it is statistically significant. After entering a variable, all variables which are in the model are tested statistically for possible removal and removed if not found significant. The mathematical description of the procedure is presented in Section II, while Section III contains the algorithm. Section IV contains details of the programming system. Control card information is provided in Section V, while section VI contains a sample problem alongwith its input and output.

# II. Mathematical description:

The stepwise multiple regression analysis is used to obtain a linear relationship between a dependent variable Y and a set of L (unknown, L  $\geqslant$  0) independent variables which are significant statistically from a set of M given variables  $X_1$ ,  $X_2$ ..... $X_M$ , when a sample of 'n' observations on them are provided.

Let  $Y_i = ith$  observation on the dependent variable for t = 1 to n

 $X_{ij} = ith$  observation on the jth independent variable for  $i=1,\ldots n$  and  $j=1,\ldots M$ 

 $w_i$  = Weighting factor for the ith observation for i = 1 to n

Now define

$$W_{i}^{(1)} = n \cdot w_{i} / \sum w_{i}$$

$$y_i = Y_i - \overline{Y}$$

$$x_{ij} = X_{ij} - \overline{X}_j$$
 for  $i = 1, \dots, n$  and  $j = 1, \dots$ 

where

1)

The leighting factors  $w_i$  are usually converted into weights i so that  $\sum w_i = n$ , the number of observations. There this is not done, then the standard error of the regression coefficients and the criterion of significance will be distorted.

The parameters A in the regression model,

$$Y = \alpha_0 \mathbf{I} + X\mathbf{I} + \boldsymbol{\epsilon} \qquad (1)$$

are given by

$$\hat{A} = (x' \mathbb{Z} x)^{-1/2} \quad x' \mathbb{Z} y \quad \dots \tag{2}$$

and

$$\hat{a}_{0} = \overline{Y} - \sum_{j=1}^{M} \hat{a}_{j} \overline{X}_{j} \dots$$
 (3)

where

Y is a n x 1 vector of deviations  $y_{i}$ 

. 1 is n x 1 vector of 1's

X is a n x Mmatrix of deviations  $x_{i,i}$ 

A is a Mix 1 vector of coefficients

 $\stackrel{\textstyle \wedge}{A}$  is a M x 1 vector of estimates of coefficients

 $\in$  is a n x 1 vector of disturbances and  $\mathbb F$  is a n x n diagonal matrix of weights

The procedure of stepwise regression analysis starts with the calculation of correlation matrix R whose elements  $r_{jk} \ \text{are given by}$ 

 $r_{jk} = S_{jk} / \int S_{jj} \int S_{kk}$  for  $j = 1, \dots M$  and  $k=1, \dots M$ 

where.

 $S_{jk} = \sum_{i=1}^{n} \mathbb{F}_{i} x_{ij} x_{ik}$  for  $j=1,\ldots M$  and  $k=1,\ldots M$  and the vector  $\mathbb{F}$  of correlation coefficients of the dependent variable with the M independent variables whose elements  $t_{j}$ , j are given by

$$t_{1j} = S1_{1,j} / \int S2 \int S_{jj}$$
 where  $S1_{1,j} = \sum_{i=1}^{n} \mathbb{V}_k x_{ij} y_i$  for  $j = 1, \dots, M$ 

$$S2 = \sum_{i=1}^{n} \mathbb{V}_{i} y_{i}^{y}$$

After the completion of calculation of correlation matrix the stepwise procedure described in the following four steps is carried out.

- 1. Select the variable, whose absolute value of the correlation with the dependent variable (d.v) is maximum. If this correlation is significant then introduce the variable into the model. If not significant then the variation in the d.v cannot be explained by any of the given set of M independent variables and hence stop the procedure.
- 2. Calculate the partial correlations controlling all the variables in the model at that stage.
- Remove the variable, whose absolute value of the partial cprrelation with the d.v. is least from the model if found not significant and then go to step 2. If found significant proceed to step 4 without removing the variable.
- Introduce the variable, whose absolute value of the partial correlation with the d.v. is highest into the model if found significant statistically and then go to step 2. If found not significant stop the procedure without introducing the variable.

## III. Algorithm:

The algorithm given by Efroymson (1960) has been used for the development of this system. His procedure is based on the gaussian elimination as described by Orden (1960) to solve a system of simultaneous equations (which are referred to in statistical terminology as normal equations).

The regression coefficients are obtained by applying linear transformations to the following partitioned matrix.

$$B = (b_{jk}) = \begin{pmatrix} R & T' \\ T & Z \end{pmatrix}$$

where R is N x N correlation matrix of independent variables (i.v's), T is a 1 x N correlation vector of i.v's with d.v, and Z a scalar, is the correlation of d.v with itself. Thus

$$b_{jk} = r_{jk}$$
 for  $j = 1, \dots M$  and  $k = 1, \dots M$ 

$$b_{k,M} f = b_{M1,k} = t_{1,k} \text{ for } k = 1, \dots M$$

$$b_{MI}$$
,  $II' = Z$ . where  $M_{I} = M + 1$ 

The following four steps depict the algorithm completely.

## Step 1:

Calculate the statistic  $V_j$  for  $j=1,\ldots N$ ; if  $b_{jj}>T^{(1)}$ , where  $V_j$  is given by

<sup>(1)</sup> It is the tolerance limit which is a small positive quantity. The tolerance on by is meant for reducing the possibility of degeneracy when independent variable is approximately equal to a linear combination of the independent variables.

$$V_{j} = b_{j,kl}$$
  $b_{kl}$ ,  $j \neq b_{jj}$ 

Calculate standard error of  $Y = St_{y} = \left(\frac{S2.b_{kl}}{D}, \frac{B1}{D}\right)^{0.5}$ 

where  $D^{(1)}$  stands for degrees of freedom.

## Step 2:

For all those  $V_j$ 's which are positive make  $a_j$ 's the regression coefficients zero, as the corresponding  $x_j$ 's are not in the model, and for those  $V_j$  0, calculate the coefficients  $a_j = b_{j,M1} \sqrt{(s_2/s_{jj})}$  since they are in the model. Also calculate std.error of  $a_j = st_j$   $(a_{jj}/s_{jj})^{0.5}$  and  $a_0 = \overline{Y} - \sum_{j=1}^{M} a_j \overline{X}_j$ 

Let  $|v_p|$  be the minimum among all  $v_j < 0$ . Remove the variable  $X_p$  from the model provided  $|v_p| \cdot D/b_{m1}$ ,  $E_1 < F_2$  (where  $F_2^{(2)}$  is the value for removing a variable) and then go to step 4 after increasing D by 1, otherwise go to step 3.

<sup>(1)</sup> Initially D takes the value  $\sum_{i=1}^{n} V_i - 1.0$ 

<sup>(2)</sup> The sequential partial F-value which is F(1, N-L-1, 0.95) or F(1, n-L-1, 0.90) where L represents the number of variables in the model at that stage.

## III. Algorithm:

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The regression coefficients are obtained by applying linear transformations to the following partitioned matrix.

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where R is N x N correlation matrix of independent variables (i.v's), T is a 1 x N correlation vector of i.v's with d.v, and Z a scalar, is the correlation of d.v with itself. Thus

$$b_{jk} = r_{jk}$$
 for  $j = 1, \dots M$  and  $k = 1, \dots M$ 

$$b_{k,M} = b_{M,k} = t_{1,k} \text{ for } k = 1, \dots M$$

$$b_{MII}$$
,  $III' = Z_{3}$  where  $M_{2} = M + 1$ 

The following four steps depict the algorithm completely.

## Step 1:

Calculate the statistic  $V_j$  for  $j=1,\ldots U_j$  if  $b_{jj}>T^{(1)}$  where  $V_j$  is given by

<sup>(1)</sup> T is the tolerance limit which is a small positive quantity. The tolerance on b is meant for reducing the possibility of degeneracy when independent variable is approximately equal to a linear combination of the independent variables.

$$V_{j} = b_{j,L1} \ ^{b}M1, j / ^{b}jj$$

Calculate standard error of  $Y = St_{y} = \left(\frac{S2.b_{M1,M1}}{D}\right)^{0.5}$ 

where  $D^{(1)}$  stands for degrees of freedom.

## Step 2:

For all those  $V_j$ s which are positive make  $a_j$ s the regression coefficients zero, as the corresponding  $x_j$ 's are not in the model, and for those  $V_j$  0, calculate the coefficients  $a_j = b_j$ , M1  $(s_2/s_j)$  since they are in the model. Also calculate std. error of  $a_j = st_j$  ( $a_{jj}/s_{jj}$ ).

Let  $|V_p|$  be the minimum among all  $V_j < 0$ . Remove the variable  $X_p$  from the model provided  $|V_p| \cdot D/b_{M1}$ ,  $M_1 < F_2$  (where  $F_2^{(2)}$  is the value for removing a variable) and then go to step 4 after increasing D by 1, otherwise go to step 3.

<sup>(1)</sup> Initially D takes the value  $\sum_{i=1}^{n} V_i - 1.0$ 

<sup>(2)</sup> The sequential partial F-value which is F(1, N-L-1, 0.95) or F(1, n-L-1, 0.90) where L represents the number of variables in the model at that stage.

## Step 3:

Let  $V_p$  be the maximum among all  $V_j > 0$ . Introduce the variable  $X_p$  into the model provided  $V_p$   $D/(b_{M1,M1}-V_p) \supset F$ , (Where  $F_1^{(1)}$  is the value for allowing a variable to enter into the model) and then go to step 4 after decreasing D by 1, otherwise stop the procedure.

## Step 4:

Let b be the diagonal element where p corresponds to the ppvariable entered or removed from the model. Update the matrix elements  $b_{.jk}$  to get the new matrix elements  $b_{.jk}^u$  where  $b_{.jk}^u$  are given by

given by
$$\begin{bmatrix}
b_{jk} & -b_{jp}b_{pj}^{u} & \text{for } j \neq p, & k \neq p \\
b_{jk} & =b_{pk}b_{pp}^{u} & \text{for } j = p, & k \neq p \\
 & =-b_{jp}b_{pp}^{u} & \text{for } j \neq p, & k = p \\
 & = 1/b_{pp} & \text{for } j = p, & k = p
\end{bmatrix}$$

where superfix 'u' indicates updated. After this step go to step 1.

Then once the model is fitted the other calculations like *E-value*,  $R^2$ ,  $\overline{R}^2$ , *RSS*, *TSS*, *ESS*, *Durbin-Vatson statistic 'd'*, first order auto correlation, expected values of d.v are performed as in the case of OMRA.

The sequential partial F value which is F(1,n-L-1,0.95) where L represents the number of variables in the model (1) at that stage.

# IV. Programming System:

The system contains a main program which calls the 'STCSR' subroutine. The main program aims at supplying object time dimensions to the subroutine 'STCSR'.

The program is quite versatile and one can fit any model which is linear in parameters to a given data. 21 transformations are provided to make the non-linear models (in variables) linear. Facilities for addition, subtraction, multiplication and division of variables are provided to generate new variables which are finally used in the regression model.

The system performs weighted or unweighted (i.e.  $w_i = 1$  for i = 1 to n) stepwise regression analysis and it can also be used to do frequency analysis  $\left(\sum_{i=1}^{n} w_i \neq n\right)$ . This package handless models with or without constants one can do OMRA using this package by simply supplying F-values as 0. However it is advisable not to use this package for OMRA as it involves additional computer time.

The system requires F-values to be provided for introducing a variable into and for removing a variable from the model. They should actually be calculated as degrees of freedom vary depending on the number of variables in the model, but F-values are supplied at fixed degrees of freedom (1, n-2), where n stands for number of observations.

The system performs all computations in double prevision. The input data is however, accepted in single precision.

The model can be linear or nonlinear in variables.

## V. Control Card Information:

This section has to be read alongwith the Control Card Information provided in Section IV of a PRL Technical Note on A Programming System on Multiple Regression Analysis.' (PRL Technical Note, TN-83-33).

In order to maintain a close proximity with the programming system 'RACSR' (PRL TN-83-33), the control cards of this system are kept similar to that of 'RACSR'. Thus control card Nos 1, 3, 5 6, 7, 8 and 9 of both the systems are identical. Control card Nos 10 and 11 of 'RACSR' system are not present in this system, hence control card No.10 of this system is similar to that of 12th control card of 'RACSR'. However some control variables in control card 2, 4 and 10 (12th in 'RACSR') are different. The first 8 control variables of control card 4 are same but the next 4 control variables differ widely. Though the control cards and the control variables of them are kept similar to that off 'RACSR', but for a few changes so that one can run both the programs with the same control cards, the following points are worth to be noted.

- 1) The method of calculation differ in both the systems.
- 2) Certain control variables which are dummy in one may not be so in other.
- 3) Certain features (like providing confidence limits on the regression coefficients) which are present in one may be absent in another.

Having seen broadly the similarities and differences of this system with 'PACSR' Programming system, let us go into the details of those control cards which differ from 'RACSR' program. For control cards similar to 'RACSR' program see PRL Technical Note TN-83-33.

# Control card 2:-

This control card is most essential in the sense that 1 to 7 additional control cards have to be supplied based on the values taken by some control variables of this card. It has 25 control variables which are read in 2512 format. All control variables are identical with 'RACSR' program but for 22nd and 23rd . However some of these control variables are dummy in the present system, i.e they won't serve the purpose for which they are used in 'RACSR' program. The details of all control variables are described below. Default options for these control variables are generally zero and they are mentioned otherwise.

and they are mentioned o	therwise.	
Control variables	Falue taken	Function/remarks
	•	
2	<b>7</b>	To read control card No.8 To form new variables involving multiplication and/or division of variables
(used alongwith control variable 1 of this card)	0	When variables take positive values, or when the power to which a variable raised is a fraction

When all or few variables take negative values

	_ 12 -	•
Control variables	Value taken	Function/remarks
Control our was	0	Input is card reader
	$\it Others$	Input unit from which data is read
<b>4</b>	Any <b>in</b> teger value <u>4</u> 50	Number of independent variables
5	Any <b>t</b> nteger value <u>4</u> 5	Number of dependent variables
6	Any integer value <u>C</u> 50	Number of coefficients to be estimated (excluding constant) + No. of dep.variables
7	0	
	1	To read control card \\No.4
8	0	_
7	₹	To read control card
9	0	
	* <b>1</b> * * * * * * * * * * * * * * * * * * *	To read control card No.7
10	0	
	1 (c)	To read control card No.8
;1 <b>*</b>	Always O	Dummy variable
12**	Always O	Dummy variable (other than O Control card 3 to be provided which is also dummy)
1 3*	Always O	Dummy variable
14	0	Input data not printed
	1	Input data printed
15**	Always O	Dummy variable (other than zero, Control card 3 to be supplied which is dummy)
16*	Always O	Dummy væriable

Control variables	Va lue	taken	Purpose/remarks
17**	Always	0 0,1	Dummy variable (3rd
			control card to be provided which is dum when value is other
18	¥'		than zero)
r de la companya di salah di s	0	•	Observed and calcular values of the depende
	*		variables are provide in their original for even if transformatic
		tion of the state	are used on dependent variables
and the state of t		<b>?</b>	e jan tiet 1
	1	<i>\(\frac{1}{2}\)</i>	m.
			They are given in transformed form of t dependent variables
19** 20*	Always O		Dummy variable. (Other than O third control card which is dummy for this program to be supplied)
20** 21	Always O	``.	Dummy variable
2000 200 - 1	1		Control card informati printed
	0		Control card informa- tion not printed
22 ed alongwith	0	- 44€- V <sub>1</sub> (1) - 1	
n.var 230 of con card 4	1	1.3713.22	Inverse of the matrix of significant variables written on
			con.var 23 of con.card No.2, con.var 1 of
			con.card 4 should also be different from zero for this to happen.

Dummy variable for this program

 $\mathbb{K} V_{+} \sim$ 

Dummy variable for this program but control card 3 should be supplied

Control variables	Valuet	aken	Purpose/remakks
23		0	
Used alongwith con.var 22	othei	than o	Output unit to write the inverse of the matrix of significant variables Control card 3 to be supplied.
24		ø	<b>-</b>
Used alongwith con.var 25	Other	than O	Total number of variables read. Control Card No.5 will be read.
		0	· · · · · · · · · · · · · · · · · · ·
n <b>25</b>	1110×	than 0	Number of new variables
	Ol Ve.	, non-	to be generated. Generates by combining variables given by con.var 24.

## Control card No.4:-

If the value taken by control variable. No.7 of control card No.2 is 1, then this card will be present and hence to be supplied. If one is running either (1) stepwise regression or (2) weighted regression or (3) regression using frequencies as weights, then one must supply this card. If one is running OMRA using this system then this control card is aptional. From this control card 13 control variables are read in 1112, 2F10.4 format. Unless specified, they take zero values by default. The details of the control variables are furnished below in tabular form. The first eight control variables of this card are same as those of 'RACSR' package.

Control variables	Value taken	
	0,2	Purpose/remarks
	0, 2	Constant included in the regression model
	<b>7</b> 1	No constant term in the
	3	Constant is present as a variable
	<b>0</b>	Noment matrix not printed
3. 3. 3. 3. 3. 3. 3. 3. 3. 3. 3. 3. 3. 3	† Always O	Moment matrix printed
4	Lucys O	Dummy variable
		<b>—</b> An
en e	7	To calculate expected values of dependent variables
5	0	
7		Durbin-Watson 'd' statistic will be printed, provided con.var 4 of this con.card takes 1  Correlation matrix printed  Means & Standard deviations are printed
Used alongwith 4th contour of this card	0,2	Observed, expected of dependent variables, their differences.
	e de la companya de l	percentage difference printed
	3	Above will not be printed

Contr	ol vari	<u>able</u> s	Valu	e taken		Purpose/remark
	9		C	)	4.	
			1	. •		Stepwise intermediate output will be given. Generally advised not to take
	1,0		0,2		ť	Least square analysis without weights carried out
		en e	1	3		Performs weighted least square analysis (Feight to be read alongwith each observation)
	11		0			- ·
			1	m diki a		reights are treated as frequencies
	12		r@a1	value		F-value to allow a variable to enter the model
.1.	13.	•	real	widlue		F-value to remove a variable from the model

#### Control card No. 10: -

6 control variables are read from this control card in 15, 12, 11, 15, 13, 464 format, and they are described below in tabular form. All control variables are same as those in 12th control card of 'RACSR' program except some change in second control variable.

Control variable	Value taken	Purpose/remarks
	Any integer	Provide end of file card. Reads as many data points, as supplied
2	0,1	Observations  Branch to 1st control card
	$2 \leq i \leq 10$	Branch to ith control card
	11, 12	Branch to 10th control card
<i>3</i>	, 13 0	Direct data
** A	1	- Rewounds input unit
4	Any integer	Number of records to be bypassed
<i>5</i>	0	No. of sets processed=1, if con.var 2 of con.card 10 is 13 To
		con.var 2 of con.card 10 is between 1 to 12 then any number of sets
6	Any integer	Number of sets to be processed
_	Any alpha-numeric data	Title of the problem

For processing first data set control cards 1, 2, 10 have to be supplied. The necessarity of other control cards namely 3 to 9 depends on the values taken by the control variables of control card 2. For processing subsequent sets (in the same run) the number and type of control cards depend on the values taken by control variables of control cards 2 and 10.

After the control cards data is provided in the format specified by the first control card, Each observation (data point) accompanied by weighting factor has to be punched on separate card(s). If  $\dot{w}_i = 1$  for all i = 1 to n then weighting factor need not be punched.

#### VI Example:-

Fit a linear mathematical model to the following data
(A. Hald-1952)

$X_{1}$	$\mathbf{X}_{2}$	$X_{\overline{\mathcal{J}}}$	$X_{4}$	¥
7	26	6	60	78.5
1	29	15	52	74.3
11	56	8	20	104.3
11	31	8	47	87.6
7	52	. 6	<i>33</i>	95.9
11	55	9	22	109.2
3	71	17	6	102.7
1	31	22	44	72.5
2	54	18	22	93.1
21	47	4	26	115.9
. 1	40	23	34	93.8
11	66	9	12	113.3
10	68	8	12	109.4

Suppose the data is punched in 5F10.1 format. The number of given data points are 13. Required output is averages, standard deviations, correlation matrix, calculated value of the d.v, difference and percentage difference between observed and calculated values, Durhin Watson 'd' statistic and an estimate of the auto-correlation. Here weights are not used, hence we will be taken as 1 for i=1 to 13. The F-values for entering and removing a variable are to be taken as 4.0 and 3.8 respectively. Given the above details the input to the program is prepared as follows:

## Input:

First control card:

1....

Column number

(5F10.1) followed by a blank card

Value

Second Control Card:

00<u>0</u>000000011111 12345678901234 <del>bbbbb</del>bb04010501

Column number

Values

Fourth Control Card:

0000000000011111111122222 123456789012345678901234

333333 012345

Column number

bbbbbb01010101

X1,00

3.8

Values

Tenth Control Card:

0000000 1 234567

Column number

bbb1 3bb

Values

After these control cards, the given data set is supplied in the format specified by first control card. Each card contains an observation having the values of  $X_1$ ,  $X_2$ ,  $X_3$ ,  $X_4$ , Y punched in that order. As weighting factors are not used  $\mathbb{F}_i$  are not necessary to punch alongwith each observation.

## Output

The minimum output that the package provides is the following. The coefficients corresponding to the variables in the model, their standard error and T-test. Regression sum of squares liean error sum of squares, Standard error of Y, Multiple correlation square ( $\mathbb{R}^2$ ), corrected R-square ( $\mathbb{R}^2$ ) and F-test.

The output for the sample problem is given below:

```
OUTPUT OF SET 1
```

```
NUMBEROFINDEPENDENT VARIABLES4NUMBEROFDEPENDENT VARIABLES1NUMBEROFTERMS5NUMBEROFOBSERVATIONS13
```

D. VAR CONSTANT 1 0.52577355D 02

D.VAR I.VAR COLF. STD. T.TEST
1 0.14683055D 01 0-12130097D 00 0.12104543D 00
2 0.66225041D 00 0.45854739D-01 0.14442355D 02

S.E.Y. M.COR.SQ. CO.M.COR.SQ. F+TEST 0.24063359D 01 0.97867835D 00 0.97441402D 00 0.22950349D 03

D.O.FR. 2 10

OBSERVED	CALCULA TED		DIFFERENCE		% DIFFERENCE TO
0.78500000D 02	0.80074004D	02	15740038D	01	20050955D ·01
0.74300003D 02	0.73250922D	02	0•10190810D	01	0.14119515D 01
0.10430000D 03	0.10581474D	03	15147350D	01	14522 <b>6</b> 68D -01
0.87600006D 02	0.89258478D	02	155\$4717D	01	18932306D 0 <b>1</b>
0.95899994D 02	0.97292514D	02	18925205D	01	19734307D .01
0.10920000D 03	0.10515249D	03	0.40475098D	01.	0.37065110D 01
0 <b>.10</b> 270000D 03	0.1040020510	03	<b></b> 13020532D	01	12678220D ·01
0.72500000D 02	0.74575423D	02	<b></b> 20754229D	01	28626523D
0.93100006D 02	0:91275488D	02	0.1 <b>82</b> 451 34D	01	0•195974.05D •01
0.11589999D 03	0 <b>.</b> 11453754D	03	0 <b>.</b> 13624545D	01	0•11755431D 01
0.83800003D 02	0.80535677D	02	0 <b>.</b> 32643265D	01	0.38953777D01
0:11330000D 03	0.11243724D	03	0.86276092D	00	0.76148350D •00
0.10939999D 03	0.11229344D	03	28934436D	01	0.26448296D -01
Durbin-Watson '	D' = 0.1921641	OD (	01 <b>,</b> Serial Co	rreI	ation= 0.391794D-01
VII. Acknowled	dgements:-				

I am thankful to Dr. (Mrs) S Rao, Dr. Dinesh Patel and Dr. B. L. K. Somayajulu for their encouragement in the preparation of this note. I am also thankful to Mr. C. A. Pathak, Mr. A. V. L. Narayana and Mr. Y. V. Pantulu for going through the manuscript and for their useful suggestions. Thanks are due to a number of scientists who utilised this system whereby helped in thoroughly testing the package. Thanks are also due to Mrs. Meena Cholishi for stenciling.

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